

CS490/590 Lecture 19: Learning Probabilistic Models

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Adapted from Roger Grosse

Overview

So far in this course: mainly supervised learning

Language modeling was our one unsupervised task; we broke it down into a series of prediction tasks

This was an example of **distribution estimation**: we'd like to learn a distribution which looks as much as possible like the input data.

Maximum Likelihood

We already used maximum likelihood in this course for training language models. Let's cover it in a bit more generality.

Motivating example: estimating the parameter of a biased coin

You flip a coin 100 times. It lands heads $N_H = 55$ times and tails $N_T = 45$ times.

What is the probability it will come up heads if we flip again?

Model: flips are independent Bernoulli random variables with parameter θ .

Assume the observations are independent and identically distributed (i.i.d.)

Maximum Likelihood

The **likelihood function** is the probability of the observed data, as a function of θ .

In our case, it's the probability of a *particular* sequence of H's and T's. Under the Bernoulli model with i.i.d. observations,

$$L(\theta) = p(\mathcal{D}) = \theta^{N_H}(1 - \theta)^{N_T}$$

This takes very small values (in this case,
 $L(0.5) = 0.5^{100} \approx 7.9 \times 10^{-31}$)

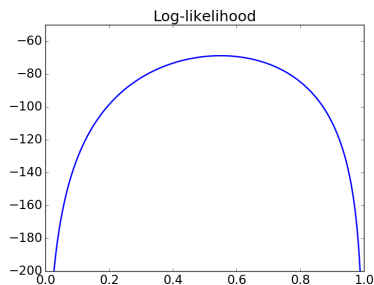
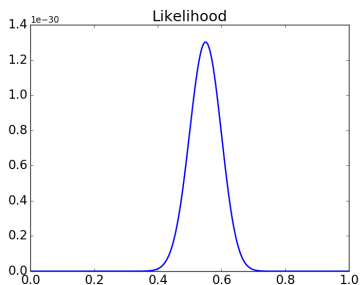
Therefore, we usually work with log-likelihoods:

$$\ell(\theta) = \log L(\theta) = N_H \log \theta + N_T \log(1 - \theta)$$

Here, $\ell(0.5) = \log 0.5^{100} = 100 \log 0.5 = -69.31$

Maximum Likelihood

$$N_H = 55, N_T = 45$$



Maximum Likelihood

Good values of θ should assign high probability to the observed data. This motivates the **maximum likelihood criterion**.

Remember how we found the optimal solution to linear regression by setting derivatives to zero? We can do that again for the coin example.

$$\begin{aligned}\frac{d\ell}{d\theta} &= \frac{d}{d\theta} (N_H \log \theta + N_T \log(1 - \theta)) \\ &= \frac{N_H}{\theta} - \frac{N_T}{1 - \theta}\end{aligned}$$

Setting this to zero gives the maximum likelihood estimate:

$$\hat{\theta}_{\text{ML}} = \frac{N_H}{N_H + N_T},$$

Maximum Likelihood

This is equivalent to minimizing cross-entropy. Let $t_i = 1$ for heads and $t_i = 0$ for tails.

$$\begin{aligned}\mathcal{L}_{CE} &= \sum_i -t_i \log \theta - (1 - t_i) \log(1 - \theta) \\ &= -N_H \log \theta - N_T \log(1 - \theta) \\ &= -\ell(\theta)\end{aligned}$$

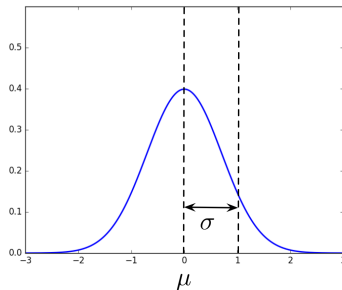
Maximum Likelihood

Recall the **Gaussian**, or **normal**, distribution:

$$\mathcal{N}(x; \mu, \sigma) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(x - \mu)^2}{2\sigma^2}\right)$$

The Central Limit Theorem says that sums of lots of independent random variables are approximately Gaussian.

In machine learning, we use Gaussians a lot because they make the calculations easy.



Maximum Likelihood

Suppose we want to model the distribution of temperatures in Toronto in March, and we've recorded the following observations:

-2.5 -9.9 -12.1 -8.9 -6.0 -4.8 2.4

Assume they're drawn from a Gaussian distribution with known standard deviation $\sigma = 5$, and we want to find the mean μ .

Log-likelihood function:

$$\begin{aligned}\ell(\mu) &= \log \prod_{i=1}^N \left[\frac{1}{\sqrt{2\pi} \cdot \sigma} \exp \left(-\frac{(x^{(i)} - \mu)^2}{2\sigma^2} \right) \right] \\ &= \sum_{i=1}^N \log \left[\frac{1}{\sqrt{2\pi} \cdot \sigma} \exp \left(-\frac{(x^{(i)} - \mu)^2}{2\sigma^2} \right) \right] \\ &= \sum_{i=1}^N \underbrace{-\frac{1}{2} \log 2\pi - \log \sigma}_{\text{constant!}} - \frac{(x^{(i)} - \mu)^2}{2\sigma^2}\end{aligned}$$

Maximum Likelihood

Maximize the log-likelihood by setting the derivative to zero:

$$\begin{aligned} 0 &= \frac{d\ell}{d\mu} = -\frac{1}{2\sigma^2} \sum_{i=1}^N \frac{d}{d\mu} (x^{(i)} - \mu)^2 \\ &= \frac{1}{\sigma^2} \sum_{i=1}^N x^{(i)} - \mu \end{aligned}$$

Solving we get $\mu = \frac{1}{N} \sum_{i=1}^N x^{(i)}$

This is just the mean of the observed values, or the **empirical mean**.

Maximum Likelihood

In general, we don't know the true standard deviation σ , but we can solve for it as well.

Set the *partial* derivatives to zero, just like in linear regression.

$$0 = \frac{\partial \ell}{\partial \mu} = -\frac{1}{\sigma^2} \sum_{i=1}^N x^{(i)} - \mu$$

$$\begin{aligned} 0 = \frac{\partial \ell}{\partial \sigma} &= \frac{\partial}{\partial \sigma} \left[\sum_{i=1}^N -\frac{1}{2} \log 2\pi - \log \sigma - \frac{1}{2\sigma^2} (x^{(i)} - \mu)^2 \right] \\ &= \sum_{i=1}^N -\frac{1}{2} \frac{\partial}{\partial \sigma} \log 2\pi - \frac{\partial}{\partial \sigma} \log \sigma - \frac{\partial}{\partial \sigma} \frac{1}{2\sigma} (x^{(i)} - \mu)^2 \\ &= \sum_{i=1}^N 0 - \frac{1}{\sigma} + \frac{1}{\sigma^3} (x^{(i)} - \mu)^2 \\ &= -\frac{N}{\sigma} + \frac{1}{\sigma^3} \sum_{i=1}^N (x^{(i)} - \mu)^2 \end{aligned}$$

$$\begin{aligned} \hat{\mu}_{\text{ML}} &= \frac{1}{N} \sum_{i=1}^N x^{(i)} \\ \hat{\sigma}_{\text{ML}} &= \sqrt{\frac{1}{N} \sum_{i=1}^N (x^{(i)} - \mu)^2} \end{aligned}$$

Maximum Likelihood

So far, maximum likelihood has told us to use empirical counts or statistics:

Bernoulli: $\theta = \frac{N_H}{N_H + N_T}$

Gaussian: $\mu = \frac{1}{N} \sum x^{(i)}, \sigma^2 = \frac{1}{N} \sum (x^{(i)} - \mu)^2$

This doesn't always happen; e.g. for the neural language model, there was no closed form, and we needed to use gradient descent.

But these simple examples are still very useful for thinking about maximum likelihood.

Data Sparsity

Maximum likelihood has a pitfall: if you have too little data, it can overfit.

E.g., what if you flip the coin twice and get H both times?

$$\theta_{\text{ML}} = \frac{N_H}{N_H + N_T} = \frac{2}{2 + 0} = 1$$

Because it never observed T, it assigns this outcome probability 0. This problem is known as **data sparsity**.

If you observe a single T in the test set, the likelihood is $-\infty$.

Bayesian Parameter Estimation

In maximum likelihood, the observations are treated as random variables, but the parameters are not.

The **Bayesian** approach treats the parameters as random variables as well.

To define a Bayesian model, we need to specify two distributions:

The **prior distribution** $p(\theta)$, which encodes our beliefs about the parameters *before* we observe the data

The **likelihood** $p(\mathcal{D} | \theta)$, same as in maximum likelihood

When we **update** our beliefs based on the observations, we compute the **posterior distribution** using Bayes' Rule:

$$p(\theta | \mathcal{D}) = \frac{p(\theta)p(\mathcal{D} | \theta)}{\int p(\theta')p(\mathcal{D} | \theta') d\theta'}.$$

We rarely ever compute the denominator explicitly.

Bayesian Parameter Estimation

Let's revisit the coin example. We already know the likelihood:

$$L(\theta) = p(\mathcal{D}) = \theta^{N_H}(1 - \theta)^{N_T}$$

It remains to specify the prior $p(\theta)$.

We can choose an **uninformative prior**, which assumes as little as possible. A reasonable choice is the uniform prior.

But our experience tells us 0.5 is more likely than 0.99. One particularly useful prior that lets us specify this is the **beta distribution**:

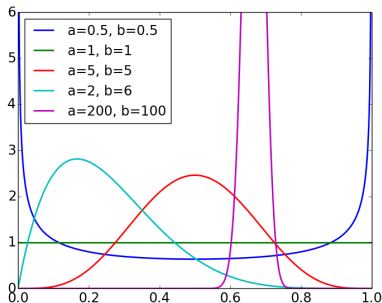
$$p(\theta; a, b) = \frac{\Gamma(a+b)}{\Gamma(a)\Gamma(b)} \theta^{a-1}(1-\theta)^{b-1}.$$

This notation for proportionality lets us ignore the normalization constant:

$$p(\theta; a, b) \propto \theta^{a-1}(1-\theta)^{b-1}.$$

Bayesian Parameter Estimation

Beta distribution for various values of a , b :



Some observations:

The expectation $\mathbb{E}[\theta] = a/(a + b)$.

The distribution gets more peaked when a and b are large.

The uniform distribution is the special case where $a = b = 1$.

The main thing the beta distribution is used for is as a prior for the Bernoulli distribution.

Bayesian Parameter Estimation

Computing the posterior distribution:

$$\begin{aligned} p(\theta | \mathcal{D}) &\propto p(\theta)p(\mathcal{D} | \theta) \\ &\propto \left[\theta^{a-1}(1-\theta)^{b-1} \right] \left[\theta^{N_H}(1-\theta)^{N_T} \right] \\ &= \theta^{a-1+N_H}(1-\theta)^{b-1+N_T}. \end{aligned}$$

This is just a beta distribution with parameters $N_H + a$ and $N_T + b$.
The posterior expectation of θ is:

$$\mathbb{E}[\theta | \mathcal{D}] = \frac{N_H + a}{N_H + N_T + a + b}$$

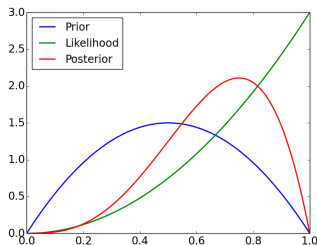
The parameters a and b of the prior can be thought of as **pseudo-counts**.

The reason this works is that the prior and likelihood have the same functional form. This phenomenon is known as **conjugacy**, and it's very useful.

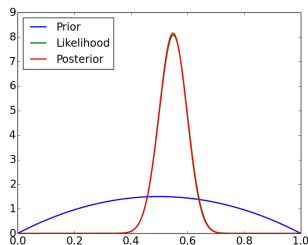
Bayesian Parameter Estimation

Bayesian inference for the coin flip example:

Small data setting
 $N_H = 2, N_T = 0$



Large data setting
 $N_H = 55, N_T = 45$



When you have enough observations, the **data overwhelm the prior**.

Bayesian Parameter Estimation (optional)

What do we actually do with the posterior?

The **posterior predictive distribution** is the distribution over future observables given the past observations. We compute this by marginalizing out the parameter(s):

$$p(\mathcal{D}' | \mathcal{D}) = \int p(\boldsymbol{\theta} | \mathcal{D}) p(\mathcal{D}' | \boldsymbol{\theta}) d\boldsymbol{\theta}. \quad (1)$$

For the coin flip example:

$$\begin{aligned} \theta_{\text{pred}} &= \Pr(x' = H | \mathcal{D}) \\ &= \int p(\theta | \mathcal{D}) \Pr(x' = H | \theta) d\theta \\ &= \int \text{Beta}(\theta; N_H + a, N_T + b) \cdot \theta d\theta \\ &= \mathbb{E}_{\text{Beta}(\theta; N_H + a, N_T + b)}[\theta] \\ &= \frac{N_H + a}{N_H + N_T + a + b}, \end{aligned} \quad (2)$$

Bayesian Parameter Estimation

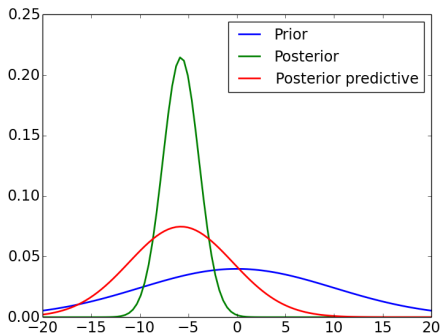
Bayesian estimation of the mean temperature in Toronto

Assume observations are i.i.d. Gaussian with known standard deviation σ and unknown mean μ

Broad Gaussian prior over μ , centered at 0

We can compute the posterior and posterior predictive distributions analytically (full derivation in notes)

Why is the posterior predictive distribution more spread out than the posterior distribution?



Bayesian Parameter Estimation

Comparison of maximum likelihood and Bayesian parameter estimation

The Bayesian approach deals better with data sparsity

Maximum likelihood is an optimization problem, while Bayesian parameter estimation is an integration problem

This means maximum likelihood is much easier in practice, since we can just do gradient descent

Automatic differentiation packages make it really easy to compute gradients

There aren't any comparable black-box tools for Bayesian parameter estimation (although Stan can do quite a lot)

Maximum A-Posteriori Estimation (optional)

Maximum a-posteriori (MAP) estimation: find the most likely parameter settings under the posterior

This converts the Bayesian parameter estimation problem into a maximization problem

$$\begin{aligned}\hat{\theta}_{\text{MAP}} &= \arg \max_{\theta} p(\theta | \mathcal{D}) \\ &= \arg \max_{\theta} p(\theta, \mathcal{D}) \\ &= \arg \max_{\theta} p(\theta) p(\mathcal{D} | \theta) \\ &= \arg \max_{\theta} \log p(\theta) + \log p(\mathcal{D} | \theta)\end{aligned}$$

Maximum A-Posteriori Estimation (optional)

Joint probability in the coin flip example:

$$\begin{aligned}\log p(\theta, \mathcal{D}) &= \log p(\theta) + \log p(\mathcal{D} | \theta) \\ &= \text{const} + (a - 1) \log \theta + (b - 1) \log(1 - \theta) + N_H \log \theta + N_T \log(1 - \theta) \\ &= \text{const} + (N_H + a - 1) \log \theta + (N_T + b - 1) \log(1 - \theta)\end{aligned}$$

Maximize by finding a critical point

$$0 = \frac{d}{d\theta} \log p(\theta, \mathcal{D}) = \frac{N_H + a - 1}{\theta} - \frac{N_T + b - 1}{1 - \theta}$$

Solving for θ ,

$$\hat{\theta}_{\text{MAP}} = \frac{N_H + a - 1}{N_H + N_T + a + b - 2}$$

Maximum A-Posteriori Estimation

Comparison of estimates in the coin flip example:

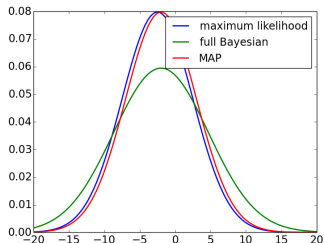
	Formula	$N_H = 2, N_T = 0$	$N_H = 55, N_T = 45$
$\hat{\theta}_{\text{ML}}$	$\frac{N_H}{N_H + N_T}$	1	$\frac{55}{100} = 0.55$
θ_{pred}	$\frac{N_H + a}{N_H + N_T + a + b}$	$\frac{4}{6} \approx 0.67$	$\frac{57}{104} \approx 0.548$
$\hat{\theta}_{\text{MAP}}$	$\frac{N_H + a - 1}{N_H + N_T + a + b - 2}$	$\frac{3}{4} = 0.75$	$\frac{56}{102} \approx 0.549$

$\hat{\theta}_{\text{MAP}}$ assigns nonzero probabilities as long as $a, b > 1$.

Maximum A-Posteriori Estimation

Comparison of predictions in the Toronto temperatures example

1 observation



7 observations

