CS490/590 Lecture 5: Multilayer Perceptrons

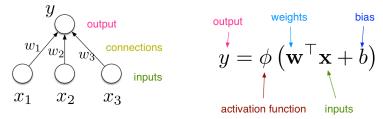
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Adapted from Roger Grosse and Jimmy Ba

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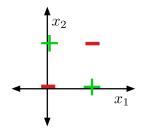
Overview

• Recall the simple neuron-like unit:



- Linear regression and logistic regression can each be viewed as a single unit.
- These units are much more powerful if we connect many of them into a neural network.

- Single neurons (linear classifiers) are very limited in expressive power.
- XOR is a classic example of a function that's not linearly separable.



• There's an elegant proof using convexity.

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Convex Sets



• A set S is convex if any line segment connecting points in S lies entirely within S. Mathematically,

$$\mathbf{x}_1, \mathbf{x}_2 \in \mathcal{S} \implies \lambda \mathbf{x}_1 + (1 - \lambda) \mathbf{x}_2 \in \mathcal{S} \text{ for } \mathbf{0} \leq \lambda \leq 1.$$

A simple inductive argument shows that for x₁,..., x_N ∈ S, weighted averages, or convex combinations, lie within the set:

$$\lambda_1 \mathbf{x}_1 + \dots + \lambda_N \mathbf{x}_N \in S \quad \text{for } \lambda_i > 0, \ \lambda_1 + \dots + \lambda_N = 1.$$

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Showing that XOR is not linearly separable

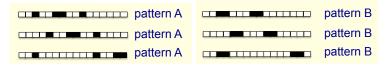
- Half-spaces are obviously convex.
- Suppose there were some feasible hypothesis. If the positive examples are in the positive half-space, then the green line segment must be as well.
- Similarly, the red line segment must line within the negative half-space.



• But the intersection can't lie in both half-spaces. Contradiction!

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A more troubling example



- These images represent 16-dimensional vectors. White = 0, black = 1.
- Want to distinguish patterns A and B in all possible translations (with wrap-around)
- Translation invariance is commonly desired in vision!

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A more troubling example



- These images represent 16-dimensional vectors. White = 0, black = 1.
- Want to distinguish patterns A and B in all possible translations (with wrap-around)
- Translation invariance is commonly desired in vision!
- Suppose there's a feasible solution. The average of all translations of A is the vector (0.25, 0.25, ..., 0.25). Therefore, this point must be classified as A.
- Similarly, the average of all translations of B is also (0.25, 0.25, ..., 0.25). Therefore, it must be classified as B. Contradiction!

• Sometimes we can overcome this limitation using feature maps, just like for linear regression. E.g., for **XOR**:

$$\psi(\mathbf{x}) = \begin{pmatrix} x_1 \\ x_2 \\ x_1 x_2 \end{pmatrix}$$

$$x_1 \quad x_2 \quad \phi_1(\mathbf{x}) \quad \phi_2(\mathbf{x}) \quad \phi_3(\mathbf{x}) \quad t$$

$$0 \quad 0 \quad 0 \quad 0 \quad 0$$

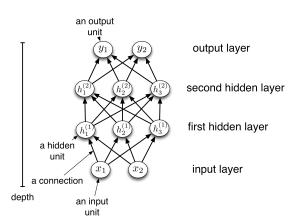
$$0 \quad 1 \quad 0 \quad 1 \quad 0 \quad 1$$

$$1 \quad 0 \quad 1 \quad 0 \quad 0 \quad 1$$

$$1 \quad 1 \quad 1 \quad 1 \quad 0$$

- This is linearly separable. (Try it!)
- Not a general solution: it can be hard to pick good basis functions. Instead, we'll use neural nets to learn nonlinear hypotheses directly.

- We can connect lots of units together into a directed acyclic graph.
- This gives a feed-forward neural network. That's in contrast to recurrent neural networks, which can have cycles. (We'll talk about those later.)
- Typically, units are grouped together into layers.

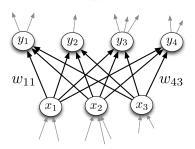


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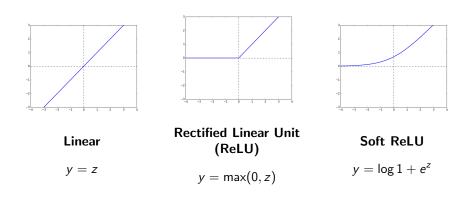
- Each layer connects N input units to M output units.
- In the simplest case, all input units are connected to all output units. We call this
 a fully connected layer. We'll consider other layer types later.
- Note: the inputs and outputs for a layer are distinct from the inputs and outputs to the network.
- Recall from softmax regression: this means we need an M × N weight matrix.
- The output units are a function of the input units:

 $\mathbf{y} = f(\mathbf{x}) = \phi \left(\mathbf{W} \mathbf{x} + \mathbf{b} \right)$

• A multilayer network consisting of fully connected layers is called a multilayer perceptron. Despite the name, it has nothing to do with perceptrons!



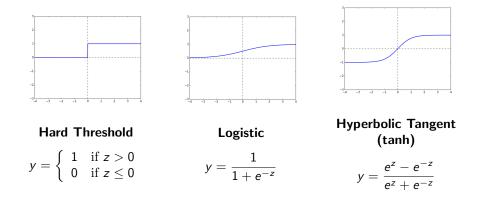
Some activation functions:



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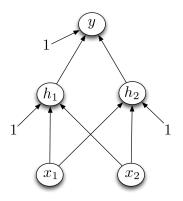


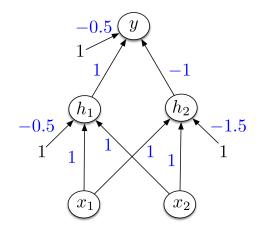
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Designing a network to compute XOR:

Assume hard threshold activation function





• Each layer computes a function, so the network computes a composition of functions:

$$h^{(1)} = f^{(1)}(\mathbf{x})$$

$$h^{(2)} = f^{(2)}(\mathbf{h}^{(1)})$$

$$\vdots$$

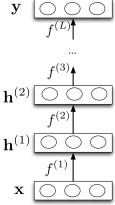
$$\mathbf{y} = f^{(L)}(\mathbf{h}^{(L-1)})$$

• Or more simply:

$$\mathbf{y} = f^{(L)} \circ \cdots \circ f^{(1)}(\mathbf{x})$$

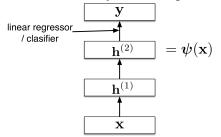
 Neural nets provide modularity: we can implement each layer's computations as a black box.





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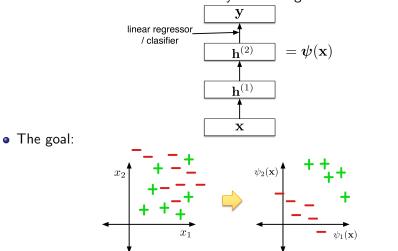
• Neural nets can be viewed as a way of learning features:



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• Neural nets can be viewed as a way of learning features:



Input representation of a digit : 784 dimensional vector.

0.0 221.0 115.0 0.0 51.0 254.0 145.0 0.0 0.0 0.0 22.0 230.0 134.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 165.0 254.0 115.0 0.0 0.0 0.0 24.0 251.0 104.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 51.0 234.0 254.0 81.0 0.0 0.0 91.0 253.0 184.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 13.0 221.0 254.0 160.0 0.0 0.0 0.0 0.0141.0254.0177.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 114.0 253.0 253.0 76.0 0.0 0.0 0.0 0.0 0.0 207.0 253.0 93.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 15.0 232.0 253.0 102.0 0.0 0.0 0.0 0.0 0.0 0.0 207.0 253.0 17.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 229.0 253.0 202.0 19.0 0.0 0.0 0.0 0.0 0.0 34.0 240.0 253.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 7.0 170.0 254.0 254.0 46.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 47.0 254.0 254.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0_0 0.0 24.0 253.0 254.0 253.0 234.0 163.0 47.0 47.0 26.0 0.0 0.0 130.0 253.0 253.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 21.0 246.0 254.0 253.0 253.0 253.0 254.0 254.0 253.0 232.0 174.0 200.0 232.0 253.0 177.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 04.0 101.0 211.0 219.0 219.0 254.0 253.0 253.0 253.0 254.0 253.0 244.0 09.0 0.0 93.0 142.0 142.0 93.0 170.0 254.0 230.0 153.0 253.0 213.0 0.0 170.0 253.0 137.0 0.0 220.0 253.0 137.0 0.0 60.0 255.0 254.0 80.0 93.0 254.0 253.0 46.0 0.0 51.0 254.0 215.0 9.0 0.0 105.0 105.0 0.0

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- Each first-layer hidden unit computes $\sigma(\mathbf{w}_i^T \mathbf{x})$
- Here is one of the weight vectors (also called a feature).
- It's reshaped into an image, with gray = 0, white = +, black = -.
- To compute $\mathbf{w}_i^T \mathbf{x}$, multiply the corresponding pixels, and sum the result.



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There are 256 first-level features total. Here are some of them.

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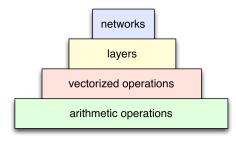
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The psychological profiling [of a programmer] is mostly the ability to shift levels of abstraction, from low level to high level. To see something in the small and to see something in the large.

- Don Knuth

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When you design neural networks and machine learning algorithms, you'll need to think at multiple levels of abstraction.



- We've seen that there are some functions that linear classifiers can't represent. Are deep networks any better?
- Any sequence of *linear* layers can be equivalently represented with a single linear layer.

$$\mathbf{y} = \underbrace{\mathbf{W}^{(3)}\mathbf{W}^{(2)}\mathbf{W}^{(1)}}_{\triangleq \mathbf{W}'} \mathbf{x}$$

- Deep linear networks are no more expressive than linear regression!
- Linear layers do have their uses stay tuned!

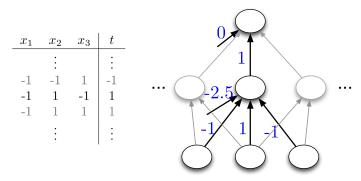
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- Multilayer feed-forward neural nets with *nonlinear* activation functions are <u>universal approximators</u>: they can approximate any function arbitrarily well.
- This has been shown for various activation functions (thresholds, logistic, ReLU, etc.)
 - Even though ReLU is "almost" linear, it's nonlinear enough!

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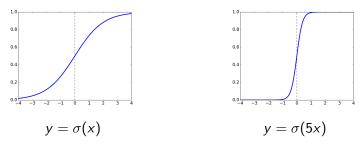
Universality for binary inputs and targets:

- Hard threshold hidden units, linear output
- Strategy: 2^D hidden units, each of which responds to one particular input configuration



• Only requires one hidden layer, though it needs to be extremely wide!

- What about the logistic activation function?
- You can approximate a hard threshold by scaling up the weights and biases:



• This is good: logistic units are differentiable, so we can tune them with gradient descent. (Stay tuned!)

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• Limits of universality

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 - You may need to represent an exponentially large network.
 - If you can learn any function, you'll just overfit.
 - Really, we desire a *compact* representation!

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- Limits of universality
 - You may need to represent an exponentially large network.
 - If you can learn any function, you'll just overfit.
 - Really, we desire a compact representation!
- We've derived units which compute the functions AND, OR, and NOT. Therefore, any Boolean circuit can be translated into a feed-forward neural net.
 - This suggests you might be able to learn *compact* representations of some complicated functions

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